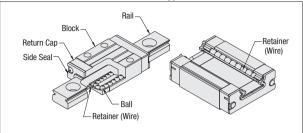
Structure and Precision of Linear Guides

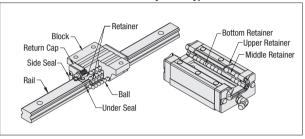
Linear Guide Preload and Allowable Load

■Linear Guide - Structure and Features

Miniature Type



Medium/Heavy Load Type



Precision

Dimensional Accuracy

Tuno	Accuracy Standards		Existing Products			C-VALUE Products
Туре			Precision Grade	High Grade	Standard Grade	Standard Grade
Miniature Type	Height H Tolerance		±10	±20	±20	±40
	Pair Variation of Height H		7	15	40	30
	Width W ₂ Tolerance		±15	±25	±25	±40
	Pair Variation of Width W2		10	20	40	30
Medium/ Heavy Load Type	Accuracy Standards		High Grade	Interchangeable	Standard Grade	Standard Grade
	Height H Tolerance		±40	±20	±100	±120
	Pair Variation of Height H		15	15	20	40
	Width W ₂ Tolerance		±20	±30	±100	±100
	Pair Variation of Width W2	24, 28	15	25	20	40
		33, 42	15	25	30	40
		30, 36, 40, 42	-	25	-	40

•	Running	Paralle	elism
		· u.u.i	

Unit: µm Miniature Medium/Heavy Load Rail Length (mm Existing Products C-VALUE Existing Products C-VALUE ecision Grade | High Grade | Standard Grade | Standard Grade | High Grade | Interchangeable | Standard Grade | Standard Grade over or Less 13 50 13 7 10 50 13 7 10 80 2 3 13 6 80 125 3 15 15 6.5 7 10 125 200 15 15 7 7 10 200 250 3.5 9 17 17 8 7 10 250 315 4 11 18 18 9 12 10 8 315 400 5 11 18 18 8 11 12 12 400 500 5 12 19 19 9 12 14 13 500 630 13.5 21 21 18 15 6 11 14 630 14 21.5 21.5 21 800 13 16 17 800 14.5 18 23 19 1000 1000 | 1250 16 20 25 22 1250 1600 23 27 23

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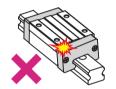
28.5 24

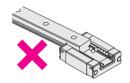
•Linear quides utilize steel balls rolling on precisely ground raceways, and the balls are recirculated by plastic return caps.

- •End seals prevent foreign substances from intruding into the blocks.
- •Miniature Type has two rows of contacting steel balls in a 4-point raceway contact design.
- •Medium/Heavy Load Types have four rows of contacting steel balls in a 2-point raceway contact design
- •Load ratings are the same for all four directions (radial, reverse-radial, and lateral directions). Can be used in any orientation.
- Cautions

Do not apply a shock to the return cap. Doing so will affect the ball circulation and may cause sliding defects.

Balls do not fall out of MISUMI linear guides when removed from rails as the blocks are equipped with ball-retainers. However, the balls may fall out by rapidly removing blocks from the rail or inserting the rail into the block at a slant. Remove and install the blocks with caution



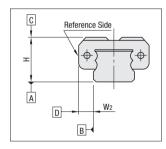


[Pair Variation of Height H]

Difference between the min./max. values of Height (H) Dimension for a number of blocks combined on one rail.

[Pair Variation of Width W2]

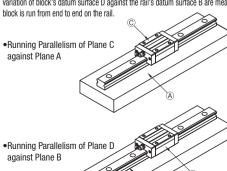
Difference between the min./max. values of Width (W) Dimension for a number of blocks combined on one rail.



[Running Parallelism]

Measured while the rail is bolted firmly to a standard datum surface base.

A relative variation of block's top surface C against the rail's bottom surface A, and a relative variation of block's datum surface D against the rail's datum surface B are measured, as the



■ Selection of Radial Clearance (Preload)

Туре		Preload	Size (Height H Dimension)	Radial Clearance (µm)
Miniature	Existing Products	Light Preload		-3~0
		Slight Clearance	6~20	0~+15
	C-VALUE Products	Normal Clearance		-3~+7
	Existing Products	Normal Clearance	24	-4~+2
			28	-5~+2
			33	-6~+3
		Interchangeable, Light Preload 30, 36, 40, 42 *42	24, 28	-4~0
Medium/			30, 36, 40, 42	-5~0
Heavy Load			-7~0	
	C-VALUE Products	Normal Clearance	24	-4~+4
			28, 30	-5~+5
			33, 36, 40	-6~+6
			45	-7~+7

^{*} marked size is for Super Heavy / Extra Super Heavy Load.

Friction Force (Required Thrust Force)

Linear Guide friction force (required thrust) varies depending on load, speed and lubricant property. Especially when moment load is applied, Preload Type friction force increases.

Although seal resistance varies according to seal lip press-fit allowance and lubrication conditions, it is not proportionate to load and keeps a constant value.

Friction force is obtained by the following formula.

 $F = \mu \cdot W + f$

F : Friction (N)

μ: Dynamic Friction Coefficient

W: Applied Load

f : Seal Resistance (2N ~ 5N)

•Clearance and preload of MISUMI Linear Guides are controlled with minute ball size

- •Increased rigidity and reduced elastic deformation will result by preloading (negative
- clearance)
- . Generally, selecting some preloads would cause favorable effects on accuracy and life of Linear Guides
- •MISUMI-manufactured Blocks and rails guarantee their own radial clearances (preload) and accuracies as sets of blocks and rails. Be sure to use the blocks and rails in sets.

Table-1. Dynamic Friction Coefficient

Туре	Dynamic Friction Coefficient (μ)
Miniature Linear Guides	0.004~0.006
Linear Guides for Medium, Heavy Load	0.002~0.003

Allowable Load

Basic Dynamic Load Rating (C)

Basic dynamic load rating is defined as: a load applied in a constant direction and ran under equal condition on a group of linear quide specimen where 90% of specimen will reach 50x103m without experiencing any damages due to rolling fatigues.

• Basic Static Load Rating (Co)

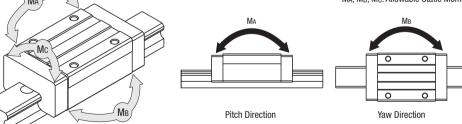
Basic static load rating is defined as: a load applied on non-moving linear guides where a sum of rolling element plastic deformation amount and rolling surface plastic deformation amount becomes equal to 0.0001 times that of the diameter of the rolling element (balls).

Allowable Static Moment (MA, MB, Mc)

Allowable static moment is a critical static moment load defined by permanent deformation value similar to basic static load rating Co.

Allowable Load (N) ≤ Co/fs Allowable Moment $(N \cdot m) \le (M_A, M_B, M_C)/f_S$

fs: Static Safety Factor Co: Basic Static Load Rating (N) Ma. MB. Mc: Allowable Static Moment (N · m)



. Static Safety Factor (fs)

Basic Static Load Rating Co, in the static state or in low speed, is divided by Static Safety Factor fs in Table - 2 depending on operating conditions.

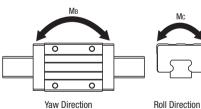


Table 2 Static Safety Factor (follower Limit

lable-2. Static Safety Factor (is Lower Limit)			
Condition of Use	Lower Limits of fs		
For normal operating condition	1~2		
When smooth running performance is required	2~4		
When vibrations and impacts exist	3~5		

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